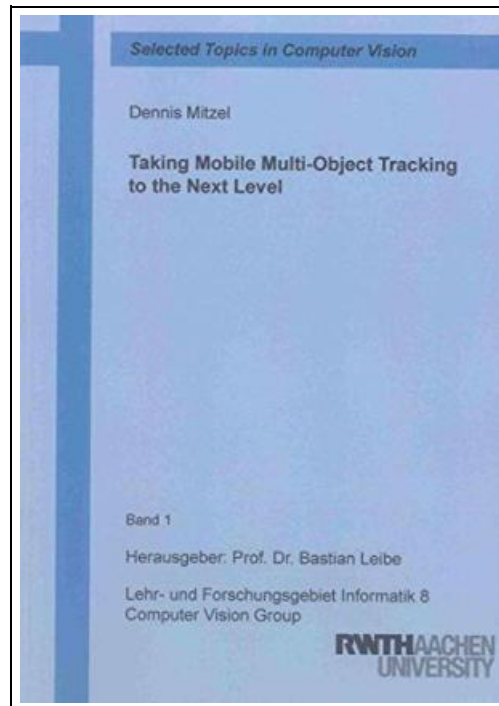


Taking Mobile Multi-Object Tracking to the Next Level



Filesize: 6 MB

Reviews

This publication is definitely not simple to begin on studying but quite fun to see. It really is full of knowledge and wisdom I am just effortlessly can get a satisfaction of studying a created pdf.

(Alfreda Bradtke)

TAKING MOBILE MULTI-OBJECT TRACKING TO THE NEXT LEVEL



Shaker Verlag Jan 2014, 2014. Buch. Condition: Neu. Neuware - Recent years have seen considerable progress in automotive safety and autonomous navigation applications, fueled by the remarkable advance of individual Computer Vision components, such as object detection, tracking, stereo and visual odometry. The goal in such applications is to automatically infer semantic understanding from the environment, observed from a moving vehicle equipped with a camera system. The pedestrian detection and tracking components constitute an actively researched part in scene understanding, important for safe navigation, path planning, and collision avoidance. Classical tracking-by-detection approaches require a robust object detector that needs to be executed in every frame. However, the detector is typically the most computationally expensive component, especially if more than one object class needs to be detected. A first goal of this thesis was to develop a vision system based on stereo camera input that is able to detect and track multiple pedestrians in real-time. To this end, we propose a hybrid tracking system that combines a computationally cheap low-level tracker with a more complex high-level tracker. The low-level trackers are either based on level-set segmentation or stereo range data together with a point registration algorithm and are employed in order to follow individual pedestrians over time, starting from an initial object detection. In order to cope with drift and to bridge occlusions that cannot be resolved by low-level trackers, the resulting tracklet outputs are fed to a high-level multihypothesis tracker, which performs longer-term data association. With this integration we obtain a real-time tracking framework by reducing object detector applications to fewer frames or even to few small image regions when stereo data is available. Reduction of expensive detector evaluations is especially relevant for the deployment on mobile platforms, where real-time performance is crucial and computational resources are notoriously limited. To...



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