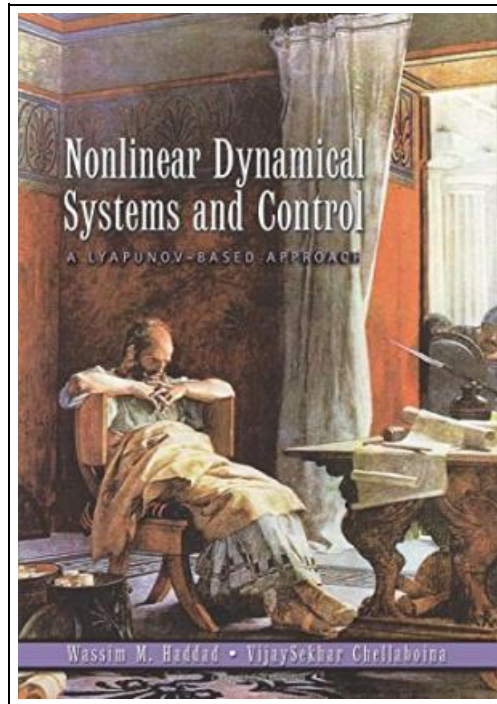# Nonlinear Dynamical Systems and Control: A Lyapunov-Based Approach

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